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MATHEMATICAL MODELS

IV SERIES

 $\mathbf{B}\mathbf{Y}$

ARNOLD EMCH



MODELS

IV SERIES

ВY

ARNOLD EMCH

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1928 UNIVERSITY OF ILLINOIS URBANA



PREFACE

The mathematical models listed and described below have been planned and designed in the mathematical laboratory of the University of Illinois since the publication of the first series in 1921, the second series in 1923, and the third series in 1925. As has been stated in the first three series, the purpose of these constructions is to represent certain features of mathematical instruction and research by adequate models, mechanisms, or graphs, which are not available in the market.

In this new series various types of illustrative mathematical technique are described.

The first is a series of lantern slides for use in lectures on algebraic geometry, in particular on algebraic curves. The figures of these slides have been selected with reference to their importance in the illustration of the theory.

Next comes a set of three models on perspective, Desargues theorem, and affinity, for use in a course on projective geometry.

Series II contains illustrations and short descriptions of two space-sextics of genus four. In the new series is added a third model of this type showing the possibility of 120 real tritangent planes of such a sextic. There is also a model of the Weddle surface, constructed by W. L. Moore in connection with a study of the geometry on this surface.

Differential geometry is represented by two models for the developability of surfaces of constant curvature.

Parties or institutions interested in these models or any of those of series I, II, III, may procure duplicates by making arrangements with local private firms for the manufacture and sale of such duplicates.

Information concerning this and possibly other questions on models will be given by Arnold Emch, Professor of Mathematics, University of Illinois.

Urbana, Illinois. January, 1928.

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MATHEMATICAL MODELS

IV Series^a

A. CLASSIFICATION OF PLANE CUBICS

Newton in his Enumeratio linearum terti ordinis,^b first published in 1704, classified plane curves of the third order into 5 types according to the values of α , β , γ in the equation

- $v^2 = a (x \alpha) (x \beta) (x \gamma):$
- I. $\alpha < \beta < \gamma$, and all real. Cubics consisting of an infinite branch and an oval = bipartite cubics.
- II. β and γ are conjugate complex. Results from III. by vanishing of isolated point.
- III. $\beta = \gamma \gtrless \alpha$. Same as I., but oval shrinks to isolated singularity.
- IV. $\alpha = \beta \ge \gamma$. Obtained from I., when infinite branch and oval join across a double point.
- V. $\alpha = \beta = \gamma$. Cubic with cusp.

As the line at infinity is a tangent to the cubic in the Newtonian form, the invariant formed by the cross-ratio of the four tangents from the infinite point of the y-axis to the cubic becomes $(\alpha\beta\gamma\infty) = (\gamma-\alpha)/(\gamma-\beta)$ and the absolute invariant.

$$J = 24 \frac{(\alpha^2 + \beta^2 + \gamma^2 - \alpha\beta - \beta\gamma - \gamma\alpha)^3}{[2(\alpha^3 + \beta^3 + \gamma^3) - 3\{\alpha\beta(\alpha + \beta) + \beta\gamma(\beta + \gamma) + \gamma\alpha(\gamma + \alpha)\} + 12\alpha\beta\gamma]^2}.$$

As this may assume any value, and as there are ∞^1 projectively different cubics, all cubics may be obtained projectively from the Newtonian five types. This was pointed out by Newton who made the statement that all cubics may be obtained from the five types by projection (shadows).

A very effective constructive treatment of the five types may be obtained by making use of the fact that cubics are invariant in certain involutorial quadratic transformations, as is shown by the author.°

The Steinerian transformation in its general form may be based upon a pencil of conics $(ax)^2 + \lambda (bx)^2 = 0$ in a plane (x), so that to

^aThe last number of series III was 31. In this, as in prospective series, the models will be num-bered continuously, so that in any inquiry concerning these models it will suffice to state the corresponding number.

^bIsaaci Newtoni Opera quae extant omnia, commen, S. Horsley, London 1779-1785, vol. 1, pp. 531-560. ^{(Newton's five types of plane cubics obtained by the Steinerian transformation. The University of Colorado Studies, vol. 1, pp. 275-284 (1904).}

a point P (y) in (x) corresponds the vertex $\{(ay) | (ax) = 0, (by) | (bx) \}$ = 0, or P' (y'), of the pencil of polars (av) (ax) + λ (bv) (bx) = 0 of (y) with respect to the pencil of conics. P and P' correspond to each other in an involutorial quadratic Cremona transformation, which has the base-points $A_1A_2A_3A_4$ of the pencil of conics as invariant points and the diagonal triangle $B_1B_2B_3$ of the quadrangle A_1A_2 A_3A_4 as the fundamental triangle. If we choose the latter as the coordinate triangle and A_4 as the unit point, such that A_1A_4 and A_2A_3 , A_2A_4 and A_3A_1 , A_3A_4 and A_1A_2 intersect in $B_1B_2B_3$ respectively, the transformation may be put in the standard form.

$$ho x_1' = x_2 x_3, \
ho x_2' = x_3 x_1, \
ho x_3' = x_1 x_2.$$

When A_4 is chosen as the orthocenter of the triangle $A_1A_2A_3$ the construction of the transformation becomes particularly simple. Let P be a generic point. Join P to B_1 and B_2 and construct the line l_1 symmetric to PB_1 with respect to B_1A_4 , l_2 symmetric to PB_2 with respect to B_2A_4 as an axis. Then l_1 and l_2 intersect in the point P', which corresponds to P in the transformation. As a check for the construction the symmetric l_3 to PB_3 with respect to B_3A_4 must also pass through P', Fig. 1.

This transformation was known to Poncelet.^a and also to Steiner^b who defined it as the correspondence between points which are simultaneously harmonic with respect to the three pairs of lines of a quadrangle, which, with $B_1B_2B_3$ as the vertices of these pairs, are $x_2 - x_3 = 0$, $x_2 + x_3 = 0$; $x_3 - x_1 = 0$, $x_3 + x_1 = 0$; $x_1 - x_2 = 0$, $x_1 + x_2 = 0$. The designation "Steinerian" for this transformation was introduced by Durège^e and adopted by Schröter,^d and others.

The procedure by which the theory of cubics may be connected with the Steinerian transformation is as follows: To a line lcorresponds a conic L which cuts l in a couple of corresponding points P, P'. These are also the double points of the involution cut out on l by the pencil of conics through $A_1A_2A_3A_4$, or the points of contact with l of two definite conics of the pencil. Conversely, with every couple P (x_1, x_2, x_3) , P' (x_2x_3, x_3x_1, x_1x_2) is, in general, uniquely associated a line l whose coordinates are $\rho u_1 = x_1 (x_2^2 - x_3^2), \rho u_2 = x_2$ $(x_3^2 - x_1^2), \ \rho u_3 = x_3 \ (x_1^2 - x_2^2).$

The locus of couples of corresponding points on the tangents of a curve $K_m(u_1, u_2, u_3) = 0$ is in general a curve of order 3m, which is invariant in the transformation. When K_m is rational then the invariant C_{3m} becomes hyperelliptic. The theory of these invari-

^aTraité des propriétés projectives des figures (1822), 2nd ed. 1865, vol. 1, pp. 185-248.
^bJ. f. Math. (Crelle's), vol. 3 (1828), pp. 207-212; Werke, vol. 1, pp. 173-180.
^cDie ebenen Curven dritter Ordnung (1871) pp. 121-128.
^dSteiner - Schröter; Vorlesungen über syn'thetische Geometrie, vol. 2, 2nd ed. (1876), pp. 301-304.



ant curves, also for general involutorial Cremona transformations in the plane, and with extensions to space, has been given by the author in a number of papers.^a

Now when K_m is a point $(a_1a_2a_3) = (a) = B$ $a_1u_1 + a_2u_2 + a_3u_3 = 0$,

we get the invariant cubic

^aSee On surfaces and curves which are invariant under involutory Cremona transformations, American Journal of Mathematics vol. 48 (1926), pp. 21-44, and references given.

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 $a_1x_1 (x_2^2 - x_3)^2 + a_2x_2 (x_3^2 - x_1^2) + a_3x_3 (x_1^2 - x_2^2) = 0$, which, with De Jonquières, we call the isologue of (a), and which passes through $A_1A_2A_3A_4$ and $B_1B_2B_3$. The joins BA_1 , BA_2 , BA_3 , BA_4 are tangents to the cubic at $A_1A_2A_3A_4$. This is a socalled Steinerian quadruple of the cubic. Moreover $BB_1B_2B_3$ is also such a quadruple, i.e., the tangents to the cubic at $BB_1B_2B_3$ are concurrent at a point C. The Steiner transformation attached to the quadruple B $B_1B_2B_3$ leaves the cubic also invariant. In this second transformation to C corresponds a point C' which, together with the diagonal triangle $C_1C_2C_3$ of $BB_1B_2B_3$ forms a new Steinerian quadruple. This process may be continued indefinitely and thus furnishes the construction of an unlimited number of points of the cubic. In the figure B is the infinite point of the serpentine.

The different Newtonian types may be obtained by this method by enumerating the various possibilities for the base-points (A) of the pencil of conics, or for the intersection of two conics.

I. THE CUBIC SERPENTINE WITH OVAL

This cubic is obtained when all four points of the fundamental triangle are either real, or imaginary. As the case of four real points is illustrated in Fig. 1, I shall now assume an entirely imaginary quadruple which is determined by the imaginary fundamental points of an elliptic coaxial system of circles and the circular points at infinity through which it also passes. Let P and Q be the limiting points of the system, Fig. 2.

P, Q and the infinite point of m form the fundamental triangle of the associated Steiner transformation. On every ray g through an arbitrary fixed point B the circles of this system cut out an involution of points whose double-points X and X' are two points of the circular cubic associated with the point B in the Steinerian transformation of the given imaginary quadruple. The points X and X' are also the points of tangency of g with two circles of the given coaxial system. Hence, according to a well known construction, the points X and X' are obtained by finding the point of intersection M of gwith m, the line joining the finite imaginary points of the quadruple. With M as a center pass a circle K through P and Q which will cut g in the required points. From the figure it is seen that the two points of the cubic on a ray through B are equally distant from m. Hence, taking a ray through B parallel to m, the point at infinity corresponding to E will be in a line a through C, which corresponds



to B, parallel to m. The tangents at B, P, Q and the real infinite point of the cubic meet at C. In other words, the line a is the real asymptote of the cubic. Considering the pencil of circles through P and Q, the same circular cubic is also produced by this pencil and the pencil of corresponding diameters through B.

II. THE CUBIC SERPENTINE

This curve is produced by assuming two separate real and two conjugate imaginary points as the fundamental quadruple. In Fig. 2, let A_1 and A_2 be the real points and the circular points of the pencil of circles through A_1 and A_2 the imaginary points. To find the points Y and Y' where a ray l through B cuts the cubic, let l cut n at N. With N as a center construct the circle L orthogomal to the pencil of circles through A_1 and A_2 , Fig. 2. The circle cuts l in the required points Y and Y'. This cubic appears, again, plainly as the product of a pencil of circles and a pencil of diameters through B. Two points Y and Y' on a ray through B are always equally distant from n. To R corresponds the infinitely distant point of the cubic; consequently the asymptote b is parallel to n and its distance SO from m is equal to RO.



Fig. 3

III. THE CUBIC SERPENTINE WITH ISOLATED POINT

The quadruple consists of two distinct points A_1A_3 and two coincident points A_2A_4 . It is assumed that the direction of the line joining A_2 with A_4 in the limit, i.e., as they become coincident, cuts A_1A_3 at B_2 . B_1 and B_2 coincide with A_2A_4 , Fig. 3. In the Steinerian transformation we find the point C corresponding to a point B, by joining B to B_1 , B_2 , B_3 and constructing the fourth harmonic rays to these joining lines with respect to the pairs of sides of the quadruple through the points B. The three fourth harmonic rays concur at the required point C. In our case the rays B_1C and B_3C coincide, as can easily be seen by passing over to the limit. As in the general case of a real quadruple, they cut the fourth harmonic ray through B_2 at C, the point through which the asymptote passes. The pencil of conics through the quadruple cuts every ray through B to the left of A_3 and the right of A_1 in elliptic involutions, and only the rays between A_1 and A_3 contain hyperbolic involutions. The only branch of the cubic is therefore contained between two lines through A_1 and A_3 parallel to the direction of B. The ray through A_2A_4 carries a parabolic involution and A_2A_4 represents an isolated point of the cubic.



Fig. 4

IV. THE NODAL CUBIC

Assuming in the fundamental quadruple A_1 and A_4 real and coincident and A_2 , A_3 conjugate imaginary, a cubic with a doublepoint, or node, at A_1A_4 arises. In Fig. 4, a vertical line through A_1A_4 represents the limiting direction of the line joining the two points. As conics of the pencil through the fundamental quadruple take the pencil of circles tangent to each other at A_1A_4 and to the vertical line. A_2 and A_3 are then represented by the circular points at infinity. To construct the cubic associated with an arbitrary point B, draw rays through B. On each of these rays the pencil of circles cuts out an involution whose double-points are points of the cubic. These points are also the points of tangency of circles of the pencil. Hence, to find the points where a ray g through B cuts the cubic, take the point M where g cuts m as a center of a circle K passing through A_1A_4 . K cuts g in the required points X and X'. From this it is seen that this cubic is also the product of a pencil of circles with coincident limiting points and a pencil of diameters through B. As X and X' are equally distant from m, the asymptote is parallel to m at a distance to the left of m equal to BA_1 ($BA_1 \perp m$ for the sake of symmetry).

V. THE CUSPIDAL CUBIC

In this case three of the four points of a real fundamental quadruple coincide. Constructively such an arrangement can be realized by assuming as the pencil of conics a pencil through a fixed point



F1G. 5

 A_1 and with its conics osculating each other at another fixed point which evidently may be considered as the representative of the three coincident points $A_2A_3A_4$.

To construct a pencil of osculating conics we may start with the fact that the picture of a circle in a perspective collineation whose center lies on the axis of collineation and also on the given circle is a conic osculating the given circle at the center of collineation.^a Hence, considering in Fig. 6^b the line *s*, joining A_1 with the coincident remaining points, as the common axis of an infinite number of perspective collineations in which only the counter-axes° vary, then the pictures of a fixed circle *K* through $A_1A_2A_3A_4$ clearly form a pencil of osculating conics.

On every ray g' (or the identical g_1') through a fixed point B (assumed infinitely distant) this pencil cuts out an involution whose double-points are two points on the cuspidal cubic associated with B in the Steinerian transformation. These points are also the points

^aFiedler: Darstellende Geometrie, Vol. I (3rd ed.), pp. 188-190.

^bThe branch of the cubic on the upper right side has only been indicated. In the construction it fell beyond the border of the figure. «See Fielder, loc. cit., pp. 47-49.

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of tangency of $g'(g_1')$ with two conics of the pencil. For the actual construction the following simple method may be applied. Let g'intersect s at S. From S draw the two tangents g and g_1 to the circle K. Through the center of collineation (cusp) draw a line lparallel to the direction of B. Let T and T_1 be the points of intersection of l with g and g_1 , and through T and T_1 draw two lines r and r_1 parallel to s. Considering r and r_1 as counter-axes of two collineations with the same axis s and the same center, then, according to the constructions of collineation, g' and g_1' are the pictures of g and g_1 in these two collineations, and the rays joining C to G and G_1 cut g' (g'_1) in two points G' and G_1 ' which evidently are the points of tangency with $g'(g_1)$ of the two osculating conics corresponding to K in the two collineations (r, r_1) . The line l cuts K at U; the tangent at U cuts s at V, and from the construction follows that the line through V, parallel to l, is the direction of an asymptote. In similar manner the lines joining C to the points of tangency W and W_1 of the tangents to K, parallel to s, are the directions of the asymptotes.

By proper collineations it is not difficult to transform the five cubics constructed by means of the Steinerian transformation into Newton's five symmetrical types.

More detailed classifications were given by Murdoch,^a Möbius,^b Cavlev.°

F. Kölmel^d from a purely algebraic standpoint and H. Wiener^e by purely geometric methods find a complete classification into 13 types based upon the values of λ in Hesse's normal form

 $x_1^3 + x_2^3 + x_3^3 + 6\lambda x_1 x_2 x_3 = 0.$

In the graphic representation of real cubics account must be taken of the behavior of these curves at infinity. The possible various shapes may be obtained from the Newtonian five types by perspective, for example by the involutorial perspective.

$$x' = \frac{x}{y - 1}$$
$$y' = \frac{y}{y - 1}$$

aGenesis Curvarum per Umbras, London 1746.

 ^bUber die Grundformen der Linien dritter Ordnung, 1852, Ges. Werke, vol. 2, p. 90.
 ^bOn the Classification of Cubic Curves, Camb. Phil. Soc. Trans., Vol. II, pp. 81-128 (1865), On Cubic Cones, same volume pp. 129-144.
 ^dAbleitung der verschiedenen Formen der Kurven dritter Ordnung durch Projektion mid Klassifika-tion derselben, 1. progr. Ettenheim, 12 pp. (1894); II. progr. Mosbach, 12 pp. (1895); III. progr. Baden-Baden, 14 pp. (1904).
 ^eDie Einteilung der ebenen Kurven und Kegel dritter Ordnung in 13 Gattungen. Halle, A. S. Schil-ling 34 pp. (1904).

ling, 34 pp. (1901).

The axis of perspective (point-wise invariant) is the line y = 0. To the line r (y = 1) corresponds the line at infinity and to the later the line q' (y = 1), so that $r \equiv q'$. By choosing the line r in distinctly different ways with respect to the cubic, we obtain by the above involution the various forms of cubics. Suppose r cuts the cubic in the points S_1 , S_2 , S_3 , and let α_1 , α_2 , α_3 be the tangents to the cubic at these points. Then the projections α'_1 , α'_2 , α'_3 of α_1 , α_2 , α_3 are the asymptotes, of the projected cubic. These may all be real, one real and two conjugate complex, one distinct and two coincident, all three coincident. Thus when d_1 in a flex-tangent, d'_1 becomes a flex-asymptote.

The list given in Figures 6, 7, 8, 9, and 10 is obtained in this manner.

Lantern slides for screen-projections of classified cubics.

32. The five Newtonian types by the Steiner transformation.

33. Types of cubics in the graphic classification (including the five Newtonian types.

IV Series

I. SERPENTINE CUBICS (UNIPARTITE)^{*}



Exciptic Sexpentine Paralolic Scepentine Hyperbolic Scepentine Diverging Parabola

Fig. 6

- I_a Elliptic serpentine. One real asymptote.
- I_b Parabolic serpentine. One real asymptote. Touches line at infinity.
- I. Hyperbolic serpentine. Three real asymptote.
- Id Diverging parabola. Has line at infinity as flex-tangent.
- Ie Serpentine with three real flex-tangents.

^aIn this list the orders of I and II are those of II and I given above, in order to have agreement with the list given in Wieleitner's Algebraische Kurven.



II. CUBIC, SERPENTINE WITH OVAL (BIPARTITE)

Fig. 7

- II_{aa} Elliptic serpentine with elliptic oval. One real asymptote.
- $\mathrm{II}_{\mathrm{ab}}$ Elliptic serpentine with elliptic oval. One real asymptote.
- II_{ac} Elliptic serpentine with hyperbolic oval. Three real asymptotes.
- $\mathrm{II}_{\mathrm{ba}}$ Parabolic serpentine with elliptic oval. One real asymptote.
- II_{bc} Hyperbolic serpentine with elliptic oval. Three real asymptotes.
- II_{da} Serpentine with elliptic oval; line at infinity as flex-tangent.
- IIe Serpentine with oval with three real flex-asymptotes.

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III. CUBIC WITH ISOLATED DOUBLE-POINT J.



F1G. 8

- III_a Elliptic serpentine with isolated double-point. One real asymptote.
- III_b Parabolic serpentine with isolated double-point. One real asymptote.
- III. Hyperbolic serpentine with isolated double-point. Three real asymptotes.
- III_d Serpentine with line at infinity as flex-tangent, with isolated double-point.
- III_e Serpentine with isolated double-point at infinity. One real asymptote.

IV. NODAL CUBICS



FIG. 9

- IV_{aa} Nodal cubic with one real asymptote.
- IV_{ab} Nodal cubic with one real asymptote and loup touching line at infinity.
- IV_{ac} Nodal cubic with three real asymptotes.
- IV_{ba} Nodal cubic with one real asymptote and open branch touching line at infinity.
- IV ca Nodal cubic with three real asymptotes.
- IV_{da} Nodal cubic with line at infinity as flex-tangent.
- IV_e Cubic with node at infinity and line at infinity cutting loop.
- IV_f Cubic with node at infinity and line at infinity cutting open branch.

V. CUSPIDAL CUBICS





- V_a Cuspidal cubic with one real asymptote.
- $V_{\rm b}$ Cuspidal cubic with one real asymptote and tangent to line at infinity.
- V_c Cuspidal cubic with three real asymptotes.
- V_d Cuspidal cubic with line at infinity as flex-tangent.
- Ve Cubic with cusp at infinity.
- $V_{\rm f}$ Cubic with line at infinity as cuspidal tangent.

B. THEORY OF CUBICS

LANTERN SLIDES FOR SCREEN-PROJECTIONS

34. Dual Singularities.

The C_3 with node at D is a Γ_4 of class 4. To the tangents of Γ_4 correspond in the polar correlation with respect to the circle C (center O) the points of a C_4 . To the double-point D (a, b) corresponds the double tangent d (A, B); to the inflexion I (f) the cusp i (F), Fig. 11.



Fig. 11

35. Self Dualistic Cuspidal Cubics.

To the cubic C_3 with cusp K(f) at K and inflexion $I(\varphi)$ at I corresponds in the polar correlation, with respect to the circle C (center O), the cubic Γ_3 with inflexion k(F) corresponding to the cusp K(f), and the cusp $i(\phi)$ corresponding to the inflexion $I(\varphi)$, Fig. 12.



FIG. 12

36. Equianharmonic Cubics.

 $E_1 = x_1 x_2^2 + x_2 x_3^2 + x_3 x_1^2 = 0.$ $E_2 = x_1 x_3^2 + x_2 x_1^2 + x_3 x_2^2 = 0.$ For both E_1 and E_2 the Hessian H is the same

$$H = x_1^3 + x_2^3 + x_3^2 - 3x_1x_2x_3 = (x_1 + x_2 + x_3)(x_1 + \epsilon x_2 + \epsilon^2 x_3) (x_1 + \epsilon^2 x_2 + \epsilon x_3) = 0.$$

The real flexes are on the unit-line $x_1 + x_2 + x_3 = 0$, and the flex-tangents at the real flexes all meet at E (111). $E_1 + \lambda E_2 = 0$ is a pencil of equianharmonics, Fig. 13.



37. Harmonic Cubic.

 $C \equiv y^2 - x^3 + 4x = 0.$ The Hessian is $H \equiv 12x^2 - 3xy^2 + 16 = 0.$ The Hessian of H is C itself, Fig. 14.



Fig. 14

38. Cubic Invariant in Involutorial Quadratic Transformation.

 $C \equiv x_1 (x_2^2 + x_3^2) + x_2 (x_3^2 + x_1^2) + x_3 (x_1^2 + x_2^2) + \lambda x_1 x_2 x_3 = 0.$ is invariant in $\rho x'_1 = x_2 x_3$, $\rho x'_2 = x_3 x_1$, $\rho x'_3 = x_1 x_2$.

P and P' are corresponding points, also a couple on cubic considered as Hessian = Steinerian of three other cubics. The join of P and P' envelopes Cayleyan class-cubic, Fig. 15.



$$u_1^{3} + u_2^{3} + u_3^{3} - u_1 (u_2^{2} + u_3^{2}) - u_2 (u_3^{2} + u_1^{2}) - u_3 (u_1^{2} + u_2^{2}) + \lambda u_1 u_2 u_3 = 0.$$

 F_1 , F_2 , F_3 are real flexes. $BB_1B_2B_3$ are here invariant points and $A_1A_2A_3$ fundamental points of transformation.

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39. Relation Between Cubic and its Hessian and Cayleyan. Choosing the cubic in the normal form

 $F \equiv x_1^3 + x_2^3 + x_3^3 + 6m x_1 x_2 x_3 = 0,$

the Hessian is

 $H \equiv x_1^3 + x_2^3 + x_3^3 + 6\mu x_1 x_2 x_3 = 0,$ in which $6\mu = -(1 + 2m^3)/m^2$.

From this is seen that for a given Hessian there are three cubics F for which the given H is the Hessian. As is well known the Hessian



is the locus of points P whose conical polars degenerate into pairs of lines. The locus of the vertices P' of these pairs coincides with H. The joins of P and P' envelope the Cayleyan, Fig. 16.

$$C \equiv m (u_1^3 + u_2^3 + u_3^3) + (1 - 4m^3) u_1 u_2 u_3 = 0$$

of class 3. It bears the same relation to the sides of the coordinate triangle as H does with respect to the vertices. H touches the flex-tangents of F and the harmonic polars of the flexes of F are the cus-

pidal tangents of C. Thus there exists duality between flexes, flextangents of F and cuspidal tangents (harmonic polars), and cusps of C. According to this dualism we can start from a class-cubic II whose 9 cusps are at the points of tangency of H, or C, with the flex-tangents of F, and whose cuspidal tangents coincide with the harmonic polars of F. C is now the Hessian of II, and H of F the Cayleyan of II.^a

40. Problems of Closure on a Cubic.

In the cubic II_{aa} let $A_1A_2A_3A_4$ be again be the invariant quadrangle of a Steinerian transformation,^b and $B_1B_2B_3$ the fundamental triangle.

Let the point B to which the invariant cubic is attached as an isologue be at infinity in the direction indicated. $A_1A_2A_3A_4$ forms a Steinerian quadruple, and the tangents at these points are concurrent at B. Likewise $BB_1B_2B_3$ form a Steinerian quadruple with point of concurrence of tangents at C_0 . The line through C_0 parallel to the direction of B is the real asymptote of the cubic. The cubic may be generated in an infinite number of ways by projective quadratic pencils around the points of a Steinerian couple (points with the same tangential) as vertices. Thus around B and B_2 , ax and a'x, and bx and b'x are two pairs of such a projectivity, intersecting in two pairs of corresponding points X, Y and X_1 , Y_1 of the Steinerian transformation. Moreover X, X_1 and Y, Y_1 form two Steinerian couples. If we join any point on the cubic to a couple, say X to B_1 and B_3 , we get another couple X', X' whose tangents have the same point of concurrence on the cubic. Through any Steinerian couple, say Y, Y_1 there are an infinite number of inscribed quadrilaterals. Thus, join Y to any point (Y') of the cubic. The join will cut the cubic in another point (B_1) . Join this point to Y_1 and find intersection with cubic at a point (Y'_1) . The join of this and Y will cut the cubic at a point (B_3) . The join of this point and Y_1 will cut the cubic at a point which will coincide with Y'. On the figure it can also easily be verfied that the 16 joins of two Steinerian quadruples pass four by four through another Steinerian quadruple, Fig. 17.

The given cubic may be considered as the Hessian of three other cubics. The three pairs of points which may be formed with a Steinerian quadruple of the given cubic are couples of corresponding points P and P' on the Hessian and Steinerian of those three cubics respectively. They belong to three distinct involutions of

^{*}See H. Wieleitner, Theorie der algebraischen Kurven höherer Ordnung, pp. 232-234 (1905).
^bArnold Emch, An introduction to projective geometry, pp. 197-204 (1905).





the second kind on the given cubic. Thus in the involution (B_1, B_3) X_1 corresponds to X. Two involutions of the first kind, when distinct, produce an involution of the second kind. Thus the Steiner involution on B sends X into Y, the Steiner involution on B_2 sends Y into X_1 . Hence the product of the two central involutions is a noncentral involution X, X_1 (of the second kind).

C. VARIOUS ALGEBRAIC CURVES

Lantern Slides for Screen-projections

41. Construction of Hyperelliptic Curves.

It is well known that an hyperelliptic curve is characterized by the existence of One g'_2 . The joins of the couples (P, P') of this series envelope in general a curve Km of class m = n - p - 1, if ndenotes the order of the hyperelliptic Cn of genus p. Such a birational transformation $(P \leftrightarrows P')$ of the Cn into itself can be incorporated in an involutorial Cremona transformation of the plane of the curve. Hence every hyperelliptic curve may be obtained as the locus of pairs of corresponding points on the tangents of rational curves in certain involutorial Cremona transformations.^a



FIG. 18

A particularly simple construction for a special involutorial quadratic transformation is obtained by choosing as the invariant quadrangle.

^aA paper by the author on the theory of such constructions will soon appear in the *Tohoku Mathematical Journal*. See also same Journal, vols. 21 (1922), pp. 310-326; 24 (1925), pp. 68-87; 25 (1925), pp. 63-76; also Am. J. of Math., vol. 48 (1926), pp. 21-44.

 $B(0, i), B_2(0, -i), B_3 = I, B_4 = J$, where I and J are the circular points at infinity, Fig. 18. The pencil of conics through these points consists of circles through the intersections of the zero circles $(x - 1)^2 + y^2 = 0$ and $(x + 1)^2 + y^2 = 0$. To find the fundamental triangle $A_1A_2A_3$ of the transformation, we have at once as A_1 the infinite point of the y-axis. A_2 in the intersection of B_1J and B_2I . A_3 that of B_1I and B_2J . The equation of B_1J is y - i = -ix, that of $B_2I y + i = +ix$, hence their intersection (1, 0). Likewise B_1I and B_2J intersect at (-1, 0). A_2 and A_3 coincide, therefore, with the centers of the zero-circles C_1 and C_{-1} . From this follows that all circles through A_2 and A_3 are invariant in the transformation. To construct T' when any point T is given, connect T to A_2 and A_3 ; draw perpendiculars p_2 and p_3 at A_2 and A_3 to TA_2 and TA_3 . Then p_2 and p_3 , the polars of T with respect to C_1 and C_{-1} , intersect at T'. Obviously, T, T' and A_2 and A_3 lie on a circle, with TT' as a diameter; hence this diameter is bisected by the y-axis at M. On every line l there are, in general, two corresponding points P and P'. To construct these, connect the point of intersection C of t and the y-axis with A_2 (or A_3), then the circle with C as a center and CA_2 as a radius cuts t in P and P'. The analytic form of the transformation^a is easily found as

$$\begin{aligned} x' &= -x\\ y' &= \frac{x^2 - 1}{y} \end{aligned}$$

An interesting problem in the theory of quadratic transformations (as a matter of fact of general Cremona transformations) is the establishment of invariant algebraic curves.

In case of a conic K_2 in a general position this locus is an invariant sextic S_6 with seven double points (i. e. of genus 3) at the A's and B's. The sextic is bicircular and has three real double points, A_1 (infinite point of y-axis), A_2 , and A_3 . The construction of this sextic is extremely simple, as shown in Fig. 18. Any tangent t of the circle K_2 cuts the y-axis in a point C. With C as a center and CA_2 as a radius describe a circle which will cut t in two points P and P' of the sextic S_6 .

42. The Analytic Triangle.

The "analytic triangle" furnishes a very effective device to analyse the graphic nature of an algebraic curve in the neighborhood

^aThis is a Steinerian transformation with two pairs of conjugate complex points forming the invariant quadruple. It was not recognized as such by M. d'Ocagne. In the preceeding explanation of the Steiner transformation the notations A and B are interchanged.



of a singularity. This method, already used by Newton,^a more fully by De Gua,^b and later systematically developed by G. Cramer,^c consists in writing the possible terms of an *n*-ic, in homogeneous coordinates x, y, z; $x^{\alpha}y^{\beta}z^{\gamma}$, $\alpha + \beta + \gamma = n$; at the vertices of a triangular latice-work, as indicated in Fig. 19, in case of a quartic. Those terms which are missing in the equation (coefficient $A_{\alpha\beta\gamma} =$ 0) are left out in the places otherwise assigned to them in the triangle. Then we connect the extreme existing and marked terms to the left and right and below by a convex polygon. The sum of the terms of the polygonal line nearest to I, or II, or III, with the proper coefficients of the equation, set equal to zero are approximation curves of the given curve if the latter passes through one, two, or three of the vertices of the coordinate triangle.

The application of this method is shown in a number of examples in some of the following slides. For this see Theorie der ebenen algebraischen Kurven höherer Ordnung by Dr. H. Wieleitner, pp. 83-118.

43. Assortment of Quartic Curves. including Quartic with 28 real double tangents.

44. Rational Quartics.

45. Quintics and Sextics.

 ^{*}Enumeratio linearum tertii ordini.—London 1704, see complete reference above.
 *P. Sauerbeck. Einleitung in die analysische Geometrie der höheren algebraischen Kurven. Nach den Methoden von Jean Paul De Gua De Malves. Teubner, 1902.
 *Introduction à l'Analyse des Lignes courbes algebriques, Genève, 1750.

D. MATHEMATICAL MODELS

46. Desargues Theorem.

If two triangles ABC and A'B'C' correspond to each other such that the joins of corresponding points A, A'; B, B'; C, C' pass through a point S, then the points of intersection A_1, B_1, C_1 of corresponding sides BC, B'C'; CA, C'A'; AB, A'B' are collinear on a line s.

Conversely when two trilaterals abc and a'b'c' correspond to each other such that the intersections of corresponding sides a, a'; b, b'; c, c' lie on a line s, then the joins a_1, b_1, c_1 of corresponding vertices bc, b'c'; ca, c'a'; ab, a'b' are concurrent at a point S.

The model illustrating this is mounted on an aluminum base on which sets the pyramid SABC made of wood with white enamel paint. The intersecting plane, made of glass cuts the pyramid at A'B'C', and rests on the base along the line s. Projecting this from a generic point upon a generic plane, the theorem stated above results.

47. Perspective.

This model illustrates relation between two planes $\Sigma(x, y)$ and $\Sigma'(x', y')$ in perspective, and its interpretation in one plane (Σ and Σ' superposed). To the line at infinity q in Σ corresponds q' (vanishing line = horizon) in Σ' . The line whose perspective r' is at infinity is denoted by r. The planes Σ and Σ' intersect in the pointwise invariant line s. The lines s, r, q' are parallel. If the center of perspective is denoted by O, then the distance from O to q' is equal to the distance of r from s, or $\overrightarrow{oq'} = \overrightarrow{rs}$. This is still true when Σ and Σ' are superposed, and any such assumption is a necessary and sufficient condition for the data of a perspective.

Fig. 20 shows the construction of the perspective K' of a circle K. Choose any line l (conveniently parallel to y-axis) cutting K in A and B. Let l cut s at S. Draw line through O parallel to l, cutting q' at Q'. Then the join of S and Q' is the perspective l' of l. OA and OB cut l' at A' and B', two points of K'. As K intersects r in two points T_1 and T_2 , with t_1 and t_2 as tangents, the perspectives of t_1 and t_2 will be tangents t'_1 and t'_2 to K' at the infinite points T'_1 and T'_2 , i.e., t'_1 and t'_2 are the asymptotes of K'. The pole M of r with respect to K is transformed into the center M' of K'.

Denoting the distances $\overrightarrow{Oq'}$ and $\overrightarrow{q's}$ by a and b, the analytic form of the perspective is easily found as



Fig. 20

$$x' = \frac{ax}{y-b}, \ y' = \frac{ay}{y-b}$$

Projecting OSA'A from U upon the y-axis we find $(OSA'A) = (OS_1 - A_1'A) = -a/b$ independent of the location of A; i.e., such a perspective has a constant cross-ratio as a characteristic. A circle $x^2 + y^2 + \alpha x + \beta y + \gamma = 0$ (by the inverse x = bx'/(y' - a), y = by'/(y' - a)) is transformed into $b^2x'^2$ ($b^2 + \beta b + \gamma$) $y'^2 + \alpha bx'y' - \alpha abx' - (a\beta b + 2a\gamma) y' + \gamma a^2 = 0$, which may represent any curve of the second order, since there are five effective constants $a, b, \alpha, \beta, \gamma$ available, which can easily be shown to be compatible with any proper choice of constants for the transformed equation.

Every conic may be obtained as the perspective of a circle.

This is the reason why curves of the second order may be properly called conics. In the figure the center of the circle has been chosen at the center O of perspective. It is easily proved that in this case O is a focus of K'.

IV Series

This constructive treatment of perspective is especially effective for the projection of infinite singularities. For example it can be made graphically plausible that the infinite point of the cubical parabola $y = x^3$ is a cusp, or that the infinite point of the semi-cubical parabola $y^2 = x^3$ is a flex. The construction becomes particularly simple when a = b. The perspective is now involutorial and the characteristic cross-ratio is -1.

The model has an aluminum base for Σ and a glass-plate for Σ' before it is made to coincide with Σ .

48. Affine Transformation Between two Planes.

The general affine relation between two planes $\Sigma'(x', y')$ and $\Sigma(x, y)$ is given by

$$x' = ax + by + c$$
$$y' = dx + ey + f$$

with the matrix $\begin{vmatrix} a & b & c \\ d & e & f \end{vmatrix}$ of rank 2.

In case of an affine homology, or perspective, there exists a pointwise invariant line. If we choose this as the x-axis, then for y = 0, there must be x' = x, y' = 0. This is only possible when

$$\begin{array}{l} x' = x + by \\ y' = ey. \end{array}$$

The joins of corresponding points are parallel and have the slope (y' - y)/(x' - x) = (e - 1)/b. If we denote two corresponding points by P and P' and the intersection of their join with the x-axis by S, then, as in perspective, the cross-ratio

$$(P'PS \infty) = P'S/PS = y'/y = e$$

is constant.

In the model the two planes Σ and Σ' are hinged along the xaxis and may be turned about it. The points of a circle in Σ and its affine figure, an ellipse, in Σ' are joined by threads which slip through the corresponding points, the threads, are the generatrices of a variable elliptical cylinder. Σ and Σ' are represented by aluminiumplates, Fig. 21.

49. The Space Sextic of Genus 4.

Models for sextics of this type are described in Series II, pp. 8-12. The object of these models is to show the six double-points of the projection of the sextic from a generic point in space upon a generic plane.



FIG. 21

As has been pointed out before the study of these sextics is of considerable importance from the standpoint of geometry as well as that of function-theory, particularly the theory of Abelian functions in connection with an algebraic curve of genus four. The canonical series is in this case a $g_{2^{n-2}}^{p-1} = g_6^3$ cut out by the linear system of cubics $\lambda_1 \phi_1 + \lambda_2 \phi_2 + \lambda_3 \phi_3 + \lambda_4 \phi_4 = 0$ through the six double-points. If we set the four linearly independent adjoints ϕ_i equal to $\rho y_i = \phi_i(x)$, i = 1, 2, 3, 4, the sextic in the plane is mapped into a non-singular sextic C_6 in S_3 of genus four, which may be shown to be the intersection of a quadric and a cubic surface. The canonical series on C_6 is now cut out by the planes.

$$\lambda_1 y_1 + \lambda_2 y_2 + \lambda_3 y_3 + \lambda_4 y_4 = 0.$$

Among the sextuples of the series those consisting of three couples of coincidences are of particular importance. Their number is obviously equal to the number of tritangent planes of C_6 .

IV Series



Fig. 22

One method to gain some insight into the configuration of these tritangent planes is by the study of the Riemamian theta functions connected with the problem. It is thus found that there are $2^{p-1}(2^p - 1) = 2^3(2^4 - 1) = 120$ point-groups of the canonical series, each consisting of three couples of coincidences. Hence the general sextic C_6 of genus four in S_3 has 120 tritangent planes.

The question may be asked, is it possible that all 120 tritangent planes may be real? Model No. 49 has been designed to show that this is possible. The sextic is obtained as the intersection of a cubic cone whose base, Fig. 23, in the plane $x_4 = 0$ may be written as

$$x_1x_2x_3 - (a_1x_1 + a_2x_2 + a_3x_3)^3 = 0,$$

MATHEMATICAL MODELS



Fig. 23

so that the sides of the coordinate triangle are flex-tangents, and a sphere. To obtain constructive symmetry, $\Sigma a_i x_i = 0$ has been chosen as the line at infinity; moreover the collineation has been arranged so that the inflexional asymptotes form an equilateral triangle. The resulting space sextic consists of 5 ovals, the maximum number possible. It has threefold symmetry with respect to three planes through a vertical diameter of the sphere, dividing this into 6 sections of 120° each. Denoting the lateral ovals by D and E, there are first $\binom{5}{3} \cdot 8 = 80$ tritangent-planes, with single contacts with the ovals. Each of the ovals A, B, C is touched twice by 6 tritangent planes, which gives 18 of this type. For each D and E, there are 3.3 = 9 tritangent-planes with double-contact, hence 2.9 = 18 of this type.

Moreover there is a plane touching D in three points, likewise one for E. Lastly there are two horizontal tritangent-planes touching A, B, C from above and from below. Thus we count altogether. 80 + 18 + 18 + 4 = 120 tritangent-planes. It must be remembered that this is no proof for the reality of all tritangent-planes, it merely shows the possibility constructively.

50. Surface of Constant Curvature.

Models of surface of rotation of constant positive curvature and of sphere upon which it can be developed. Made of wood. A de-



FIG. 24

formable hollow thin brass-shell shows how these surfaces are mutually developable.

51. Weddle Surface (By W. L. Moore).

and

The surface belongs to the class of determinant surfaces, this one being the Jacobian of the four quadrics

 $x^2 + y^2 + z^2 - (x + y + z) = 0,$ xy - 4xz + 3yz = 0. $3(x^2 + xy - x) - (z^2 + yz - z) - 2xz = 0,$ $5(y^2 + xy - y) - 2(z^2 + xz - z) - 3yz = 0,$ on the six points

 $A_1(0, 0, 0), A_2(1, 0, 0), A_3(0, 0, 1), A_4(0, 1, 0), A_5(1, 1, 1),$

and $A_6(1/3, 2/3, -1/3)$. Geometrically it is the locus of vertices of quadric cones through the six points.

Its equation is

$$\begin{vmatrix} 2x-1 & 2y-1 & 2z-1 & -x-y-z \\ y-4z & x+3z & -4x+3y & 0 \\ 5y-2z & 5x+10y-3z-5 & -2x-3y-4z & 2 & -5y+2z \\ 6x+3y-2z-3 & 3x-z & -2x-y-2z+1 & -3x+z \end{vmatrix} = 0$$

or

 $(x + y + z - 1) [4x^2y - 4xy^2 + 2x^2z - 2xz^2 + 2yz^2 - 2y^2z + xy - 4xz + 3yz] - 2xyz (3x - 2y - z) = 0.$

The model shows the six nodes, the fifteen lines joining the nodes in pairs, the ten lines which are the intersections of the pairs of planes through the nodes, and the space cubic through the six nodes. This cubic is in any case an asymptotic line of the corresponding Weddle Surface. The plane sections are represented by beads outlining the quartic curves thus giving several systems of quartic curves on the surface.